

PURPOSE

- To present the development of a passive unilateral hip brace for gait training
- Long-term objective: use the hip-brace in a future research study to influence asymmetric gait patterns by introducing errors

INTRODUCTION

Why design a passive unilateral hip brace?

- Many individuals with neurological diseases (e.g., Multiple Sclerosis or Stroke) experience asymmetric gait patterns [1,2]
 - Reduced overall preferred walking speed Reduced lower extremity ROM (affected limb) Reduced step lengths (affected limb)
- Robotic exoskeletons (wearable devices) have proven successful at influencing the kinetics and kinematics of walking gait [3,4]

up such devices, and the time to prepare subjects themselves is significant

 Passive exoskeletons reduce the price of materials and offer a less-time consuming method for influencing gait Offers the possibility of wearing the device for an extended period outside of a lab environment • "Error augmentation" offers a promising avenue to treat

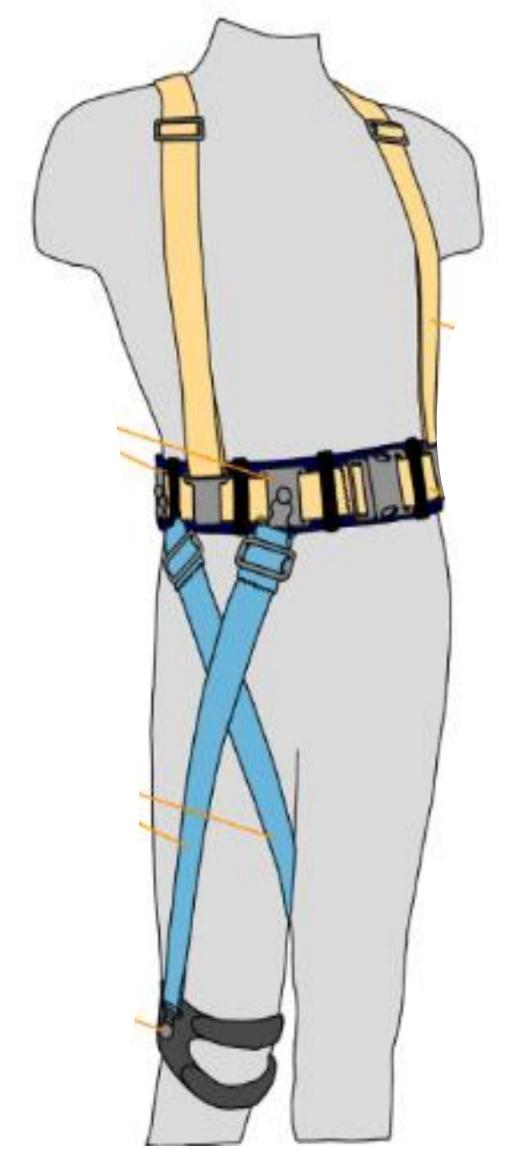
asymmetric gait patterns

Increasing walking errors (i.e., moving limbs) from their normal trajectories) [4] The brain develops new patterns (neural motor through error – providing pathways) an interesting research avenue for new rehabilitation protocols [3,5]



Design of a Low-cost Unilateral Hip Brace for Gait Training

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design of the proposed exoskeleton (right) [2]..

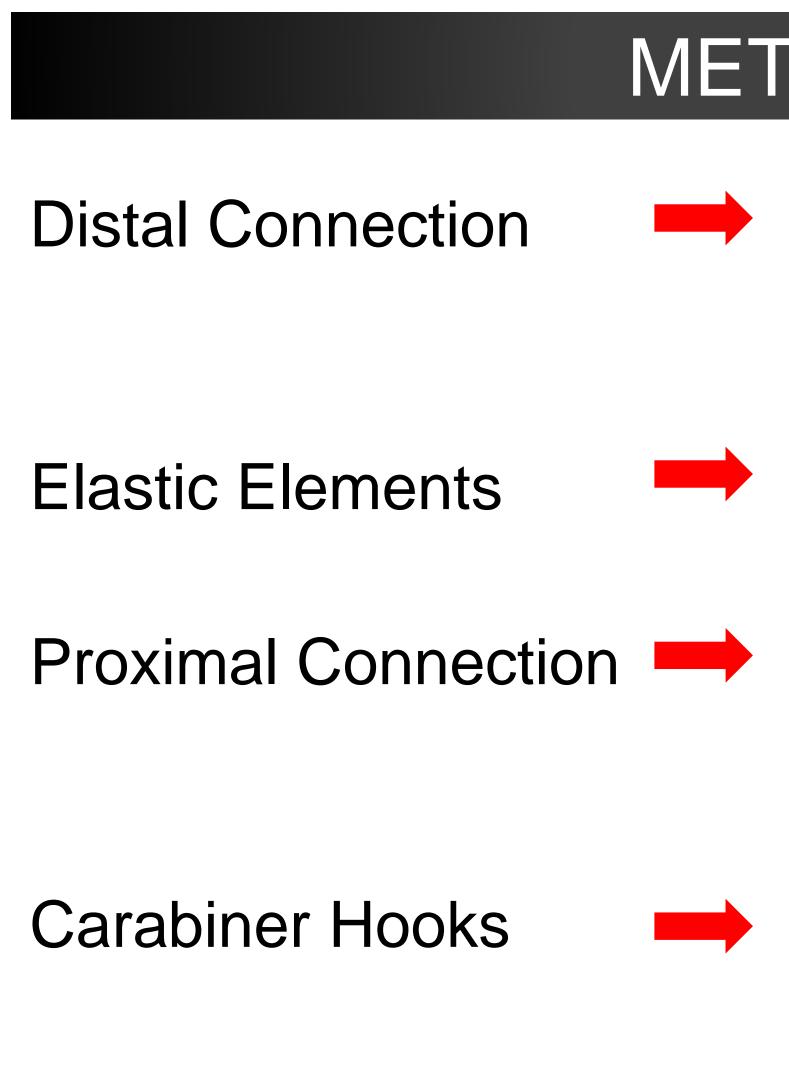




Figure 1: Example of a previous design (left) of a unilateral exoskeleton and the

METHODS

- Surfer Calf SBS Two Straps
- Two TheraBand® Strips
- Proflex[®] Back Brace with Built-in Suspender Straps
- Allows for a quick connection to the distal and proximal segments of the exoskeleton

RESULTS & DISCUSSION

Basis for Brace Design

- Sclerosis patients effectiveness [2]

Planned Use for Error Augmentation

pretension

Increases errors experienced at the hip during walking

- impede walking [6]
- walking gait

We expect that, once removed, exaggerated hip extension will occur – possibly restoring symmetry

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• The brace design is based on a previous research design by Neuman et al. seen in Figure 1 on the left • The device successfully assisted hip flexion in Multiple displaying the designs ____

Bands will be stretched past optimum actuation

Providing suboptimal actuation assistance was found to

Using the bands to create more errors rather than for assistive purposes establishes a method to impose error augmentation on walking gait

• The bands seen in Figure 1 resist hip extension during

REFERENCES

[1] Ramakrishnan T, et al. *Front Neurobot* **12**, 1-12, 2018. [2] Neuman RM, et al. *Res Sq*, 1-19, 2020. [3] Kao PC, et al. *Phys Med Rehabil Int* **2**, 1-15, 2015. [4] Selinger J, et al. *Curr Biol* **25**, 2452-2456, 2015. [5] Patton JL, et al. *Neurorehabilitation Technology*, 73-85, 2012. [6] Nuckols RW, et al. *J Neuroeng Rehabil* **17**, 1-19, 2020.

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